



# The Carel Driver

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The Carel driver connects to a network of Carel air-conditioning and refrigeration packaged controls. Available for Commander and ObSys.

This document relates to Carel driver version 2.0

Please read the *Commander Manual* or *ObSys Manual* alongside this document, available from [www.northbt.com](http://www.northbt.com)

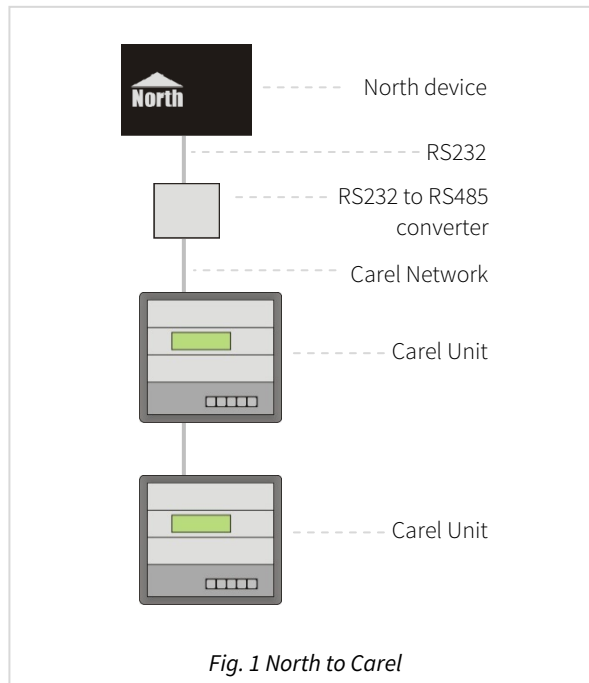
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# Compatibility with the Carel System

The Carel driver allows North to interface with a Carel air-conditioning and refrigeration packaged control system.

The driver connects via an RS485 serial connection to a network of Carel controllers, each fitted with an RS485 interface card (Fig. 1). Up to 32 controllers can be connected, dependant on model.



## Equipment

Carel controllers that are compatible with the driver include:

- pCO series – pCO, pCO1, pCO2, pCO3
- mP20
- $\boxtimes$ AC/FCM, microAC

The following controls are also compatible, when using additional hardware:

- ASM2, mP3/hP3 – this requires an RS232 to RS422 converter for the COM port
- $\boxtimes$ Chiller – requires a Carel ISA72 interface card

Carel OEM-controls may be branded by various air-conditioning and refrigeration companies, including:

- Airedale
- Climaventa
- Klima-Therm
- McQuay
- RC Group
- Trane
- Uniflair
- York

## Values

The data from a controller is accessed from a list of analogue, integer and digital values. To understand these values you will need a list of data points from the manufacturer.

Depending on the model, brand, and application firmware, each controller can typically have the following values available:

- Remote start/stop
- Setpoint
- Alarm limits
- Output status
- Sensor values
- Alarm status

## Prerequisites

The Carel controllers should be networked using the RS485 supervisor network. Each controller must be configured with a unique address in the range 1...207, and a baud rate of 19200 as described below.

An RS232-485 adapter is required and must be set to 19200 baud, 11 data bits.

You will require a list of the data points available in the Controller from the product distributor.

### pCO<sub>2</sub>

Fit the RS485 serial card (ref. PCO2004850) to the serial card expansion slot in the pCO<sub>2</sub> unit. From the display, access the user parameters by pressing the 'Prog' key. Enter the user password and configure the following parameters on page Pf:

Parameter	Value
Identific. number for BMS	1...200
Comm. Speed	19200
Protocol type	Carel

From the manufacturers parameters (accessed by pressing 'Menu' and 'Prog') the following parameter can also be set to allow control by the driver:

Menu	Parameter	Value
Configuration	BMS Network	Yes

### pCO

Fit the RS485 serial card (ref. PCO1004850 or PCOSER0000) to the 9-pin connector J7 on the pCO board. If applicable, set the jumper to RS485 communication. From the display, access the service menu and configure the following parameters:

Menu	Parameter	Value
Remote Control	I/O via Serial	Yes
	Id #	1...16
	Speed	19200

### MAC

Fit the RS485 serial card (ref. MAC2SER000) to the MAC display unit. From the MAC display, access the user parameters by pressing the 'Alarm' key for 5 seconds. Enter the password and configure the following parameters:

Parameter	Description	Value
Ho	Address of MAC on supervisor network	1...200
HP	Baud rate of supervisor network	5=19200

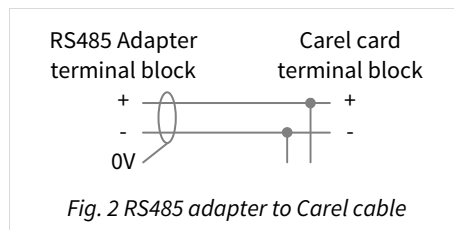
# Using the Driver

On ObSys and Commander, the Carel driver is pre-installed. On all of these North devices, you can use the driver to create an interface to Carel. Once started, you will need to set up the driver before it can communicate with the Carel system.

## Making the Cable

Connect the North device COM port to an RS232 to RS485 adapter.

Using the RS485 cable specification (Fig. 2), connect the RS485 adapter to the Carel RS485 card.



RS485 adapters are available from North, order code MISC/RS232/485.

## Starting the Interface

- 🖥️ To start an interface using the Carel driver, follow these steps:
  - **Start Engineering** your North device using ObSys
  - Navigate to **Configuration, Interfaces**, and set an unused **Interface** to 'Carel' to start the particular interface
  - Navigate to the top-level of your North device and re-scan it

The driver setup object (Mc), labelled **Carel Setup**, should now be available. If this object is not available, check an interface licence is available and the driver is installed.

## Setting up the Driver

- 🖥️ To set up the driver, follow these steps:
  - Navigate to the **Carel Setup** object (Mc). For example, if you started interface 1 with the driver earlier, then the object reference will be 'M1'
  - Set the **RS232 Com Port** (RS.COM) to the COM port you are connecting to Carel with

## Checking Communications

You can check that the interface is communicating by reading the **Comms Established** object (DS). A value of 'Yes' indicates the driver has connected to, and is communicating with, the Carel network.

# Object Specifications

Once an interface is started, one or more extra objects become available within the top-level object of the device. As with all North objects, each of these extra objects may contain sub-objects, (and each of these may contain sub-objects, and so on) – the whole object structure being a multi-layer hierarchy. It is possible to navigate around the objects using the ObSys Engineering Software.

Each object is specified below, along with its sub-objects.

## Example Object Reference

An example of a reference to an object in the same device: the Carel System (S1) contains Unit 1 (U1), which contains an Analogue (A), which contains a Value (O1). Therefore, the object reference will be 'S1.U1.A.O1'.

An example of a reference to an object in a different device: the IP network object (IP) contains Default Commander object (CDIP), which contains the object above (S1.U1.A.O1) – therefore the complete object reference is 'IP.CDIP.S1.U1.A.O1'.

## Device Top-Level Objects

When an interface is started using the Carel driver, the objects below become available within the top-level object of the device. For example, if Interface 1 is started, then the object with references 'M1' and 'S1' become available.

Description	Reference	Type
<b>Carel Setup</b> Set up the Carel driver, started on interface <i>c</i> ( <i>c</i> is the interface number)	Mc	Fixed Container: On the Commander platform this will be <i>[CDM v20\Carel v20]</i> On the Integrator and ObSys platforms this will be <i>[OSM v20\Carel v20]</i>
<b>Carel System</b> Access Carel system connected to interface <i>c</i> ( <i>c</i> is the interface number)	Sc	Variable Container: Typically this will be <i>[Carel v20]</i> If Carel Unit Type is configured, this will be a fixed container in the format <i>[Carel v20\Unit Type]</i> , e.g. <i>[Carel v20\MicroAC]</i> In Direct Connect mode, this will be <i>[Carel v20\Unit]</i>

# Carel Driver Setup

Object Type: [OSM v20\Carel v20]

Object Type: [CDM v20\Carel v20]

The Carel driver contains the following objects:

Description	Reference	Type
<b>RS232 Com Port</b>	RS.COM	Obj\Num; Range: 1...8; Adjustable
<b>Baud Rate</b> Baud rate of the Carel RS485 network. 19200 is recommended.	RS.BR	Obj\Num; Range: 4800...19200; Adjustable
<b>Device Label</b> Label displayed when scanning the system	DL	Obj\Text; Max. 20 characters; Adjustable
<b>Comms Established</b>	DS	Obj\NoYes
<b>Direct Connect</b> Set to Yes when connecting with one device only, to use the broadcast address	DC	Obj\NoYes; Adjustable
<b>Legacy Support</b> Set to Yes when connecting with older equipment: pCO controllers with a BIOS dated before 23/7/97, or ASM2 controllers via an RS232/422 converter. When Legacy Support is enabled do not use addresses 17, 18, 20, 25, 35 or 37	LS	Obj\NoYes; Adjustable
<b>Carel Unit Type</b> Leave blank to enable scanning of the contents by the driver. If a fixed contents file is available, enter the folder name here, e.g. 'MicroAC' or 'MicroC2'	DT	Obj\Text; Max. 20 characters; Adjustable
<b>Rescan Network</b> Set to Yes to force the driver to rescan the Carel network. Use this after adding new controllers to the network or changing an address	RN	Obj\NoYes; Adjustable
<b>Maximum Address</b> Set this object to the highest address on the Carel network. Setting this object avoids the driver scanning the full 207 address range	MA	Obj\Num; Range: 1...207; Adjustable
<b>Units Detected</b> Reports the number of controllers found on the network	UC	Obj\Num; Range: 0...32
<b>CRC Errors</b> Reports the number of corrupted messages received. A high error count may indicate noise on the RS485 network	EC	Obj\Num

# Carel System

Object Type: *[Carel v20]*

The Carel System contains a network of up to 32 controllers.

If the Carel network is changed the driver should be told to re-scan the network using the 'Rescan Network' object (RN) found in the Carel Setup object.

Description	Reference	Type
<b>Unit x</b> The unit address, <i>x</i> , is a number in the range 1...207	U <i>x</i>	Typically this will be a variable container: <i>[Carel v20\Unit]</i> If Carel Unit Type is configured, this will be a fixed container in the format <i>[Carel v20\Unit Type]</i> , e.g. <i>[Carel v20\MicroAC]</i>



# Carel Unit

Object Type: *[Carel v20\Unit]*

Each Carel Unit contains a list of analogue, integer and digital type values.

The Carel protocol only sends values that have changed. On starting, the driver scans the Carel network for available controllers and requests all their values. The driver then stores these values within its memory, regularly requesting changed values from each controller.

Description	Reference	Type
<b>Parameters</b> General controller information	P	Fixed Container: <i>[Carel v20\Para]</i>
<b>Analogue Values</b>	A	Variable Container: <i>[Carel v20\Unit\Ana]</i>
<b>Integer Values</b>	I	Variable Container: <i>[Carel v20\Unit\Int]</i>
<b>Digital Values</b>	D	Variable Container: <i>[Carel v20\Unit\Dig]</i>

# Carel Parameters

Object Type: [Carel v20\Para]

The Carel Parameters object contains information about the drivers' communication with a Carel packaged controller:

Description	Reference	Type
<b>Communicating</b> Unit is responding to requests for data	S	Obj\NoYes
<b>Hardware Version</b>	V	Obj\Num
<b>Hardware Description</b>	VL	Obj\Text
<b>Hardware BIOS</b>	B	Obj\Enum: 0...3 Values: 0=unknown, 1=Macroplus, 2=Standard pCO, 3=pCO in pLAN
<b>Analogue Count</b> Number of analogue values available	MA	Obj\Num: 0...207
<b>Integer Count</b> Number of integer values available	MI	Obj\Num: 0...207
<b>Digital Count</b> Number of digital values available	MD	Obj\Num: 0...207

## Carel Analogue Values

Object Type: *[Carel v20\Unit\Ana]*

A Carel unit contains the following analogue objects:

Description	Reference	Type
<b>Analogue <math>x</math></b> The analogue number, $x$ , is in the range 1...207	Ox	Obj\Float: -3276.7...3276.7; Adjustable

## Carel Integer Values

Object Type: *[Carel v20\Unit\Int]*

A Carel unit contains the following Integer objects:

Description	Reference	Type
<b>Integer <math>x</math></b> The digital number, $x$ , is in the range 1...207	Ox	Obj\Num: -32767...32767; Adjustable

## Carel Digital Values

Object Type: *[Carel v20\Unit\Dig]*

A Carel unit contains the following Digital objects:

Description	Reference	Type
<b>Digital <math>x</math></b> The digital number, $x$ , is in the range 1...207	Ox	Obj\OffOn; Adjustable

# MicroAC Unit

Object Type: [Carel v20\MicroAC]

A Carel  $\mu$ AC fixed function air-conditioning controller contains the following objects:

Description	Reference	Type
<b>Communicating</b>	P.S	Obj\NoYes
<b>Version Description</b>	P.VL	Obj\Text
<b>Analogue Count</b> Number of analogue values available	P.MA	Obj\Num: 0...207
<b>Integer Count</b> Number of integer values available	P.MI	Obj\Num: 0...207
<b>Digital Count</b> Number of digital values available	P.MD	Obj\Num; 0...207
<b>Analogue Values</b>	A	Fixed Container: [Carel v20\MicroAC\Ana]
<b>Integer Values</b>	I	Fixed Container: [Carel v20\MicroAC\Int]
<b>Digital Values</b>	D	Fixed Container: [Carel v20\MicroAC\Dig]

# MicroAC Analogue Values

Object Type: [Carel v20\MicroAC\Ana]

A MicroAC unit contains the following analogue values:

Description	Reference	Type
<b>Probe B3</b>	O1	Obj\Float
<b>Probe B1</b>	O2	Obj\Float
<b>Probe B2</b>	O3	Obj\Float
<b>Probe B4</b>	O4	Obj\Float
<b>Working Set</b>	O5	Obj\Float
<b>Temp Setpoint (cooling)</b>	O11	Obj\Float; Adjustable; -20...60
<b>Temp Setpoint (heating)</b>	O12	Obj\Float; Adjustable; -20...60
<b>Min Temp Setpoint</b>	O13	Obj\Float; Adjustable; -20...60
<b>Max Temp Setpoint</b>	O14	Obj\Float; Adjustable; -20...60
<b>Cooling Differential</b>	O15	Obj\Float; Adjustable; 0.1...11
<b>Heating Differential</b>	O16	Obj\Float; Adjustable; 0.1...11
<b>Temp Dead Zone</b>	O17	Obj\Float; Adjustable; 0.1...20
<b>Humidity Setpoint (%rH)</b>	O18	Obj\Float; Adjustable; 0...100
<b>Min Hum Setpoint</b>	O19	Obj\Float; Adjustable; 0...100
<b>Max Hum Setpoint</b>	O20	Obj\Float; Adjustable; 0...100
<b>Hum Differential (%rH)</b>	O21	Obj\Float; Adjustable; 0...20
<b>Dehum Differential (%rH)</b>	O22	Obj\Float; Adjustable; 0...20
<b>Humidity Dead Zone</b>	O23	Obj\Float; Adjustable; 0...20
<b>Authority for Compensation</b>	O24	Obj\Float; Adjustable; -2...2
<b>Cooling SP Compensation</b>	O25	Obj\Float; Adjustable; -20...60
<b>Heating SP Compensation</b>	O26	Obj\Float; Adjustable; -20...60
<b>Free Cooling Differential</b>	O27	Obj\Float; Adjustable; 0...30
<b>Lower Supply Temp Limit (Free Cooling)</b>	O28	Obj\Float; Adjustable; -20...30
<b>Low Temp Alarm Delta</b>	O29	Obj\Float; Adjustable; 0...50
<b>High Temp Alarm Delta</b>	O30	Obj\Float; Adjustable; 0...50
<b>Low Hum Alarm Delta</b>	O31	Obj\Float; Adjustable; 0...50
<b>High Hum Alarm Delta</b>	O32	Obj\Float; Adjustable; 0...50
<b>Return-Supply Delta</b>	O33	Obj\Float; Adjustable; 0...20
<b>% Reg Band Min</b>	O34	Obj\Float; Adjustable; 0...100
<b>% Reg Band Max</b>	O35	Obj\Float; Adjustable; 0...100
<b>Probe B3 Minimum</b>	O36	Obj\Float; Adjustable; 0...100
<b>Probe B3 Maximum</b>	O37	Obj\Float; Adjustable; 0...100
<b>Probe B1 Calibration</b>	O38	Obj\Float; Adjustable; -6...6
<b>Probe B2 Calibration</b>	O39	Obj\Float; Adjustable; -6...6
<b>Probe B3 Calibration</b>	O40	Obj\Float; Adjustable; -10...10
<b>Probe B4 Calibration</b>	O41	Obj\Float; Adjustable; -6...6

# MicroAC Integer Values

Object Type: [Carel v20\MicroAC\Int]

A MicroAC unit contains the following Integer values:

Description	Reference	Type
<b>Cold Valve Open (%)</b>	O1	Obj\Num
<b>Heat Valve Open (%)</b>	O2	Obj\Num
<b>0-10V Output (%)</b>	O3	Obj\Num
<b>1 Phase-cut Output (%)</b>	O4	Obj\Num; Adjustable; 0...30000
<b>Supply Fan Hour Counter</b>	O11	Obj\Num; Adjustable; 0...30000
<b>Filter Hour Counter</b>	O12	Obj\Num; Adjustable; 0...30000
<b>Comp 1 Hour Counter</b>	O13	Obj\Num; Adjustable; 0...30000
<b>Comp 2 Hour Counter</b>	O14	Obj\Num; Adjustable; 0...30000
<b>Supply Fan Hour Threshold</b>	O15	Obj\Num; Adjustable; 0...30000
<b>Filter Hour Threshold</b>	O16	Obj\Num; Adjustable; 0...30000
<b>Comp Hour Threshold</b>	O17	Obj\Num; Adjustable; 0...30000
<b>Machine Model</b>	O18	Obj\Enum; Adjustable; 0...3 Values: 0=ED unit, 1=CE unit, 2=CW unit (C/H), 3=Shelter unit
<b>Cooling Operating Mode</b>	O19	Obj\Enum; Adjustable; 0...4 Values: 0=Comp 1, 1=Comp 2, 2=3-point valve, 3=2 different comp, 4=comp in tandem
<b>Heating Operating Mode</b>	O20	Obj\Enum; Adjustable; 0...4 Values: 0=None, 1=1 element, 2=2 elements, 3=3-point valve, 4=2 different elements
<b>Humidifier Present</b>	O21	Obj\NoYes
<b>3P valve Excursion Time (s)</b>	O22	Obj\Num; Adjustable; 0...600
<b>Temperature Regulation</b>	O23	Obj\Enum Adjustable; 0...1 Values: 0=Prop Only, 1=Prop & Integral
<b>Integration time for PI (s)</b>	O24	Obj\Num; Adjustable; 10...3600
<b>Dehumidification type</b>	O25	Obj\Enum; Adjustable; 0...9 Values: 0=Comp 1, 1=Comp 2, 2=Both Comp, 3=Cooling Ramp, 4=Fan Speed Reduction (FSR), 5=FSR/Comp, 6=FSB/Comp, 7=FSR/Both Comp, 8=FSR/Cool Ramp, 9=None
<b>Probe B2 Function</b>	O26	Obj\Enum; Adjustable; 0...4 Values: 0=Setpoint, 1=Free Cooling, 2=3-point control, 3=PUT3, 4=Condensation
<b>Probe B3 Function</b>	O27	Obj\Enum; Adjustable; 0...1 Values: 0=Humidity, 1=Condensation
<b>Output Y2 Function</b>	O28	Obj\Enum; Adjustable; 0...2 Values: 0=Supply Fan, 1=Cond Fan/Press, 2=Cond Fan/Temp
<b>ID1 Present</b>	O29	Obj\NoYes
<b>Alarm Relay Function</b>	O30	Obj\Enum; Adjustable; 0...3 Values: 0=Off All, 1=On All, 2=Off Serious, 3=On Serious
<b>Hum Relay Function</b>	O31	Obj\Enum; Adjustable; 0...7 Values: 0=On Dehum, 1=Off Dehum, 2=Non-serious Alarm, 3=Rotation, 4=On Hum, 5=Off Hum, 6=Fan 2 On, 7=Fan 2 Off
<b>Alarm ID5 Reset Function</b>	O32	Obj\Enum; Adjustable; 0...6 Values: 0=None, 1=Alm Auto, 2=Alarm Man, 3=Auto, 4=Man, 5=Serious Alm Auto, 6=Serious Alm Man
<b>Machines in Rotation</b>	O33	Obj\Num; Adjustable; 0...6
<b>Unit in Rotation</b>	O34	Obj\Num; Adjustable; 0...6
<b>Rotation Time (hrs)</b>	O35	Obj\Num; Adjustable; 0...250

Description	Reference	Type
<b>Air Probe B2</b>	036	Obj\Enum; Adjustable; 0...1 Values: 0=None, 1=NTC Carel
<b>Type of Probe B3</b>	037	Obj\Enum; Adjustable; 0...2 Values: 0=None, 1=0-1v or 0-20mA, 2=4-20 mA
<b>Supply Air Probe B4</b>	038	Obj\Enum; Adjustable; 0...1 Values: 0=None, 1=NTC Carel
<b>Digital Filter</b>	039	Obj\Num; Adjustable; 1...15
<b>Input Limit</b>	040	Obj\Num; Adjustable; 1...15
<b>Keypad Lock</b>	041	Obj\OffOn; Adjustable
<b>Parameter Set (HL)</b>	042	Obj\Num; Adjustable; 0...3
<b>Data Displayed</b>	043	Obj\Enum; Adjustable; 0...2 Values: 0=Probes, 1=Set Points, 2=Day/Time
<b>Buzzer Activation</b>	044	Obj\Num; Adjustable; 0...15
<b>Reset Alarms (P5)</b>	045	Obj\Num; Adjustable; 0...5
<b>Unit Address</b>	046	Obj\Num; Adjustable; 0...200
<b>Unit Baudrate</b>	047	Obj\Enum; Adjustable; 1...5 Values: 1=1200, 2=2400, 3=4800, 4=9600, 5=19200
<b>User Password</b>	048	Obj\Num; Adjustable; 0...200
<b>Software Version</b>	049	Obj\Num
<b>Fan Operation</b>	050	Obj\Enum; Adjustable; 0...2 Values: 0=Always On, 1=Prop w/Min Speed, 2=Prop w/Cut-off
<b>Min Triac Threshold</b>	051	Obj\Num; Adjustable; 0...100
<b>Max Triac Threshold</b>	052	Obj\Num; Adjustable; 0...100
<b>Triac Impulse (ms)</b>	053	Obj\Num; Adjustable; 0...15
<b>Min Output Value (%)</b>	054	Obj\Num; Adjustable; 0...100
<b>Max Output Value (%)</b>	055	Obj\Num; Adjustable; 0...100
<b>Min On Time (s)</b>	056	Obj\Num; Adjustable; 0...300
<b>Min Off Time (s)</b>	057	Obj\Num; Adjustable; 0...900
<b>Time between 2 start-ups (s)</b>	058	Obj\Num; Adjustable; 0...900
<b>On delay between 2 Comp (s)</b>	059	Obj\Num; Adjustable; 0...300
<b>Off delay between 2 Comp (s)</b>	060	Obj\Num; Adjustable; 0...300
<b>Comp On Delay (s)</b>	061	Obj\Num; Adjustable; 0...300
<b>Supply Off Fan Delay (s)</b>	062	Obj\Num; Adjustable; 0...900
<b>Delay on Start-up (s)</b>	063	Obj\Num; Adjustable; 0...300
<b>Compressor Rotation</b>	064	Obj\OffOn; Adjustable
<b>Flow Alarm Delay on Start (s)</b>	065	Obj\Num; Adjustable; 0...250
<b>Flow Alarm Delay Op (s)</b>	066	Obj\Num; Adjustable; 0...90
<b>Low Press Alarm Delay (s)</b>	067	Obj\Num; Adjustable; 0...250
<b>Temp/Hum Alarm Delay (min)</b>	068	Obj\Num; Adjustable; 0...150
<b>Generic Alarm Delay (s)</b>	069	Obj\Num; Adjustable; 0...250
<b>Time Band Setting</b>	070	Obj\Enum; Adjustable; 0...2 Values: 0=Disabled, 1=Min Speed, 2=On/Off
<b>Fan Pick-up Time in Cond (s)</b>	071	Obj\Num; Adjustable; 0...60

# MicroAC Digital Values

Object Type: [Carel v20\MicroAC\Dig]

A MicroAC unit contains the following Digital values:

Description	Reference	Type
<b>Alarms Active</b>	01	Obj\NoYes
<b>Buzzer</b>	02	Obj\OffOn
<b>EPROM Alarm</b>	03	Obj\NoYes
<b>Probe B1 Fail</b>	04	Obj\NoYes
<b>Probe B2 Fail</b>	05	Obj\NoYes
<b>Probe B3 Fail</b>	06	Obj\NoYes
<b>Probe B4 Fail</b>	07	Obj\NoYes
<b>Clock Fail</b>	08	Obj\NoYes
<b>C1 High Pressure Alarm</b>	09	Obj\NoYes
<b>C2 High Pressure Alarm</b>	010	Obj\NoYes
<b>C1 Low Pressure Alarm</b>	011	Obj\NoYes
<b>C2 High Pressure Alarm</b>	012	Obj\NoYes
<b>Air Flow Alarm</b>	013	Obj\NoYes
<b>Dirty Filter Alarm</b>	014	Obj\NoYes
<b>Heating Elements Alarm</b>	015	Obj\NoYes
<b>Fan Overload Alarm</b>	016	Obj\NoYes
<b>Compressor Overload Alarm</b>	017	Obj\NoYes
<b>High Supply Temp Alarm</b>	018	Obj\NoYes
<b>Humidifier Alarm</b>	019	Obj\NoYes
<b>Low Ambient Temp Alarm</b>	020	Obj\NoYes
<b>High Ambient Temp Alarm</b>	021	Obj\NoYes
<b>Low Ambient Hum Alarm</b>	022	Obj\NoYes
<b>High Ambient Hum Alarm</b>	023	Obj\NoYes
<b>Generic Alarm</b>	024	Obj\NoYes
<b>Fan Hour Counter Alarm</b>	025	Obj\NoYes
<b>Filter Hour Counter Alarm</b>	026	Obj\NoYes
<b>Comp 1 Hour Counter Alarm</b>	027	Obj\NoYes
<b>Comp 2 Hour Counter Alarm</b>	028	Obj\NoYes
<b>Low Power during EPROM write</b>	029	Obj\NoYes
<b>Power Fail</b>	030	Obj\NoYes
<b>Unit Status</b>	033	Obj\OffOn
<b>Comp 1 Status</b>	034	Obj\OffOn
<b>Comp 2 Status</b>	035	Obj\OffOn
<b>Heater 1 Status</b>	036	Obj\OffOn
<b>Heater 2 Status</b>	037	Obj\OffOn
<b>Fan Status</b>	038	Obj\OffOn
<b>Dehum Status</b>	039	Obj\OffOn
<b>Clock Board Present</b>	040	Obj\NoYes
<b>Hum Relay Status</b>	041	Obj\OffOn
<b>Unit On/Off Switch</b>	049	Obj\OffOn; Adjustable
<b>Temperature Units</b>	050	Obj\Enum; Adjustable; 0...1 Values: 0=°C, 1=°F



# Driver Versions

Version	Build Date	Details
2.0	1/3/2003	Driver re-design implementing protocol version 3.0s
2.0	4/4/2011	Improved handling of communications when unit does not respond
2.0	20/8/2013	Baud rate set to 19200 on initialization

## Next Steps...

If you require help, contact support on 01273 694422 or visit [www.northbt.com/support](http://www.northbt.com/support)



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Document issued 16/07/2015.